Neural networks

Sparse coding - dictionary update with block-coordinate descent

Topics: dictionary update (algorithm 2)

Going back to our original problem

$$\min_{\mathbf{D}} \frac{1}{T} \sum_{t=1}^{T} \min_{\mathbf{h}^{(t)}} l(\mathbf{x}^{(t)}) = \min_{\mathbf{D}} \frac{1}{T} \sum_{t=1}^{T} \frac{1}{2} ||\mathbf{x}^{(t)} - \mathbf{D} \mathbf{h}(\mathbf{x}^{(t)})||_{2}^{2} + \lambda ||\mathbf{h}(\mathbf{x}^{(t)})||_{1}$$

- Let's assume $\mathbf{h}(\mathbf{x}^{(t)})$ doesn't depend on \mathbf{D} (which is false)
 - we must minimize

$$\min_{\mathbf{D}} \frac{1}{T} \sum_{t=1}^{T} \frac{1}{2} ||\mathbf{x}^{(t)} - \mathbf{D} \mathbf{h}(\mathbf{x}^{(t)})||_{2}^{2}$$

we must also constrain the columns of **D** to be of unit norm

Topics: dictionary update (algorithm 2)

- An alternative is to solve for each column $D_{\cdot,j}$ in cycle:
 - \blacktriangleright setting the gradient for $\mathbf{D}_{\cdot,j}$ to zero, we have

$$0 = \frac{1}{T} \sum_{t=1}^{T} (\mathbf{x}^{(t)} - \mathbf{D} \mathbf{h}(\mathbf{x}^{(t)})) h(\mathbf{x}^{(t)})_{j}$$

$$0 = \sum_{t=1}^{T} \left(\mathbf{x}^{(t)} - \left(\sum_{i \neq j} \mathbf{D}_{\cdot,i} h(\mathbf{x}^{(t)})_{i} \right) - \mathbf{D}_{\cdot,j} h(\mathbf{x}^{(t)})_{j} \right) h(\mathbf{x}^{(t)})_{j}$$

$$\sum_{t=1}^{T} \mathbf{D}_{\cdot,j} h(\mathbf{x}^{(t)})_{j}^{2} = \sum_{t=1}^{T} \left(\mathbf{x}^{(t)} - \left(\sum_{i \neq j} \mathbf{D}_{\cdot,i} h(\mathbf{x}^{(t)})_{i} \right) \right) h(\mathbf{x}^{(t)})_{j}$$

$$\mathbf{D}_{\cdot,j} = \frac{1}{\sum_{t=1}^{T} h(\mathbf{x}^{(t)})_{j}^{2}} \sum_{t=1}^{T} \left(\mathbf{x}^{(t)} - \left(\sum_{i \neq j} \mathbf{D}_{\cdot,i} h(\mathbf{x}^{(t)})_{i} \right) \right) h(\mathbf{x}^{(t)})_{j}$$

ightharpoonup we don't need to specify a learning rate to update $\mathbf{D}_{\cdot,j}$

Topics: dictionary update (algorithm 2)

- An alternative is to solve for each column $D_{\cdot,j}$ in cycle:
 - we can rewrite

$$\mathbf{D}_{\cdot,j} = \frac{1}{\sum_{t=1}^{T} h(\mathbf{x}^{(t)})_{j}^{2}} \sum_{t=1}^{T} \left(\mathbf{x}^{(t)} - \left(\sum_{i \neq j} \mathbf{D}_{\cdot,i} h(\mathbf{x}^{(t)})_{i} \right) \right) h(\mathbf{x}^{(t)})_{j}$$

$$= \frac{1}{\sum_{t=1}^{T} h(\mathbf{x}^{(t)})_{j}^{2}} \left(\left(\sum_{t=1}^{T} \mathbf{x}^{(t)} h(\mathbf{x}^{(t)})_{j} \right) - \sum_{i \neq j} \mathbf{D}_{\cdot,i} \left(\sum_{t=1}^{T} h(\mathbf{x}^{(t)})_{i} h(\mathbf{x}^{(t)})_{j} \right) \right)$$

$$= \frac{1}{A_{j,j}} (\mathbf{B}_{\cdot,j} - \mathbf{D} \mathbf{A}_{\cdot,j} + \mathbf{D}_{\cdot,j} A_{j,j})$$

this way, we only need to store:

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$$\mathbf{A} \longleftarrow \sum_{t=1}^{T} \mathbf{h}(\mathbf{x}^{(t)}) \ \mathbf{h}(\mathbf{x}^{(t)})^{\top}$$

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$$\mathbf{B} \longleftarrow \sum_{t=1}^{T} \mathbf{x}^{(t)} \mathbf{h}(\mathbf{x}^{(t)})^{\top}$$

Topics: dictionary update (algorithm 2)

- While D hasn't converged
 - lackbox for each column $\mathbf{D}_{\cdot,j}$ perform updates

$$\mathbf{D}_{\cdot,j} \longleftarrow \frac{1}{A_{j,j}} \left(\mathbf{B}_{\cdot,j} - \mathbf{D} \; \mathbf{A}_{\cdot,j} + \mathbf{D}_{\cdot,j} \; A_{j,j} \right)$$

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$$\mathbf{D}_{\cdot,j} \longleftarrow rac{\mathbf{D}_{\cdot,j}}{||\mathbf{D}_{\cdot,j}||_2}$$

- This is referred to as a block-coordinate descent algorithm
 - a different block of variables are updated at each step
 - the "blocks" are the columns $\mathbf{D}_{\cdot,j}$